# **Non-equilibrium Thermodynamics** Balance of mass and of entropy Local equilibrium principle

Most of the real processes are non-equilibrium. Their direction is determined by the II law of Thermodynamics. For isolated system (not exchanging energy with the surrounding)  $\frac{dS}{dt} \ge 0$ 

### **Second Postulate (temperature)**

Every **equilibrium** system is completely determined by the set of external variables (volume, pressure, magnetic field, etc.) plus one internal variable – **TEMPERATURE.** 

For nonequilibrium systems in addition to temperature some other internal variables  $\mathbf{x}_i$  are needed.

### Out of equilibrium some more internal parameters are needed in addition to temperature to describe the system

$$dG = -SdT + pdV - \sum_{i} A_{i} d\mathbf{x}_{i}$$
$$A_{i} = -\left(\frac{\partial G}{\partial \mathbf{x}_{i}}\right)_{P,T,\mathbf{x}_{i}} \mathbf{AFINITY}$$

Nemilov formulated a criterion that two order parameters  $\mathbf{x}_i$  and  $\mathbf{x}_j$  are independent

$$\frac{\left(\frac{\partial \mathbf{V}}{\partial \boldsymbol{x}_{i}}\right)_{\mathrm{p,T}}}{\left(\frac{\partial \mathbf{S}}{\partial \boldsymbol{x}_{i}}\right)_{\mathrm{p,T}}} \neq \frac{\left(\frac{\partial \mathbf{V}}{\partial \boldsymbol{x}_{j}}\right)_{\mathrm{p,T}}}{\left(\frac{\partial \mathbf{S}}{\partial \boldsymbol{x}_{j}}\right)_{\mathrm{p,T}}}$$

## hydrodynamic approximation

It is assumed that the large macrosystem can be divided to small subsystems. The size of each is small as compared to the whole system and large as compared to molecules (atoms) so that methods of statistics are applicable. This will be OK if the deviation of parameters  $\mathbf{a}_i$  from the equilibrium values  $\mathbf{a}_o$  are small. For instance the temperature change at distance *l* is small as compared to temperature itself.

$$\left|\frac{l}{\boldsymbol{a}_{i}} \operatorname{grad} \boldsymbol{a}_{i}\right| \ll 1$$

Actually, this means that Gibbs equation is applicable in local form

 $Tds = du - pdv - \sum m_i dn_i$ 

$$T\frac{ds}{dt} = \frac{du}{dt} - p\frac{dv}{dt} - \sum \mathbf{m}_i \frac{dn_i}{dt}$$

The overall entropy in any moment is  $S = \int s dv$ 

The usual procedure involves the equations of balance of mass and entropy (or energy)

If *E* is the local value of some extensive property

$$\frac{\partial E}{\partial t} = -divJ_E + \boldsymbol{S}_E$$

The conservation law means that the product of *E* inside the subsystem is not possible, i.e.  $\mathbf{s}_{E}=0$  (*E*=mass, energy, etc.)

*examples* For multicomponent closed system  $\frac{\partial \mathbf{r}_{i}}{\partial t} = -divJ_{\mathbf{r}_{i}} + \mathbf{S}_{\mathbf{r}_{i}}$ 

In framework of Newtonian mechanics the conservation law claims  $\sum \mathbf{s}_{ri} = 0$  with  $\mathbf{r} = \sum \mathbf{r}_i$ 

$$\frac{\partial \mathbf{r}}{\partial t} = -divJ_{I}$$

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where  $J_r = \sum J_{ri} = \sum \mathbf{r}_i u_i$ ;  $u_i$  is the average speed of the  $i^{th}$  component  $J_i = \mathbf{r}_i (u_i - u_o) + \mathbf{r}_i u_o$  (\*)

The average mass rate of the system is  $u_o = \frac{\sum r_i u_i}{r}$ 

In (\*) the second term accounts for the convective flux while the first term accounts for the diffusive flux.

Entropy balance  

$$\frac{\partial s}{\partial t} = \sum \left( \frac{\partial s}{\partial \mathbf{r}_i} \right) \frac{\partial \mathbf{r}_i}{\partial t}$$
As soon as  $\frac{\partial s}{\partial \mathbf{r}_i} = -\frac{\mathbf{m}_i}{T} \implies \frac{\partial s}{\partial t} = -\sum \frac{\mathbf{m}_i}{T} \frac{\partial \mathbf{r}_i}{\partial t}$  (\*\*)

If a chemical reaction j is taking place at a rate (per unit volume)  $w_j$  with stoichiometric coefficient  $\mathbf{n}_{j}$  then from the balance of mass:

$$\boldsymbol{s}_{ri} = \sum \boldsymbol{n}_{ij} \boldsymbol{w}_j$$

Therefore: 
$$\frac{\partial \boldsymbol{r}_j}{\partial t} = -divJ_j + \sum \boldsymbol{n}_{ij}w_j$$
 With Eq.(\*\*) this gives:

$$\frac{\partial s}{\partial t} = -\sum_{i} \sum_{j} \frac{\boldsymbol{m}}{T} \boldsymbol{n}_{ij} \boldsymbol{w}_{j} + \sum_{i} \frac{\boldsymbol{m}}{T} di \boldsymbol{v} \boldsymbol{J}_{i} =$$
$$= \sum_{j} \left[ -\sum_{i} \frac{\boldsymbol{m}}{T} \boldsymbol{n}_{ij} \right] \boldsymbol{w}_{j} + di \boldsymbol{v} \sum_{i} \frac{\boldsymbol{m}}{T} \boldsymbol{J}_{i} - \sum_{i} \boldsymbol{J}_{i} \nabla \frac{\boldsymbol{m}}{T}$$

The Affinity of the *j*<sup>th</sup> reaction

$$A_{j} = -\sum_{j} m_{ij} \text{ it can be presented also as: } A_{j} = kT \ln \frac{K^{eq}(T.p)}{\prod_{j} r_{j}^{n_{ij}}}$$

The equilibrium constant of reaction is:  $K^{eq}(T, p) = \prod_{i} \mathbf{r}_{j,eq}^{\mathbf{n}_{ij}}$ 

At equilibrium  $A^{eq} = 0$ . It is seen that affinity is a measure of declination from equilibrium state. It play a role similar to **Num**in transport theory.

$$\frac{\partial s}{\partial t} = \sum_{j} \frac{A}{T} w_{j} - \sum_{j} J_{i} \nabla \frac{\mathbf{m}_{i}}{T} + div \sum_{i} \frac{\mathbf{m}_{i}}{T} J_{i}$$

This expression can be considered as consisting of two terms:

$$\boldsymbol{s}_{s} \equiv \sum_{j} \frac{A}{T} w_{j} - \sum J_{i} \nabla \frac{\boldsymbol{m}_{i}}{T}$$

and

$$divJ_s = div\sum_i \frac{\mathbf{m}_i}{T}J_i$$

It is seen that  $\mathbf{s}_{i}$  is a bilinear function of  $J_{j}$  and  $w_{j}$  (generalized fluxes)  $J_{k}$  related to nonreversible processes. It is as well a bilinear form of  $\nabla \frac{\mathbf{m}_{i}}{T}$  and  $\frac{A_{i}}{T}$  that could be considered as generalized forces  $X_{k}$  causing the fluxes.

$$\boldsymbol{s} = \sum \boldsymbol{J}_k \boldsymbol{X}_k$$

$$\frac{\partial s}{\partial t} = \mathbf{s}_s - div \mathbf{J}_s$$

If we integrate the last equation over the volume, from the condition of mechanical equilibrium and the *div* rule:

$$\frac{\partial S}{\partial t} = \int \mathbf{S} dv_{s} - \int div J_{s} dv = \int \mathbf{S} dv_{s} - \int_{S} \mathbf{n} J_{s} d\mathbf{S} \equiv \frac{\partial_{e} S}{\partial t} + \frac{\partial_{i} S}{\partial t}$$

 $\Sigma$  is the surface *n* is the unit vector

For isolated system the flux of entropy across the system is  $\frac{\partial_e S}{\partial t} = 0$ .

The II law of thermodynamics states  $\frac{\partial_i S}{\partial t} \ge 0$ 

Therefore,  $\mathbf{S}_{S} \geq 0$  when the method of local description is OK

### **PRIGOGINE RATIO**

## It is often useful to describe Affinity as:

$$A_{i} = \left(\frac{\partial G}{\partial \boldsymbol{x}_{i}}\right)_{T,p,\boldsymbol{x}_{j}}$$
$$dG = -SdT + pdV - \sum_{i} A_{i}d\boldsymbol{x}_{i}$$

$$dG = -SdT + pdV - \sum A dx$$

# Mixed derivatives of a function of state are equal

$$\frac{\partial \mathbf{V}}{\partial \boldsymbol{x}} = \frac{\partial^2 \mathbf{G}}{\partial \mathbf{P} \partial \boldsymbol{x}} = \frac{\partial^2 \mathbf{G}}{\partial \boldsymbol{x} \partial \mathbf{P}} = -\frac{\partial \mathbf{A}}{\partial \mathbf{P}}$$

compressibility

$$k = -\frac{1}{V_o} \left( \frac{\partial V}{\partial P} \right)_T \quad \Rightarrow \quad \Delta k = -\frac{1}{V_o} \left( \frac{\partial V}{\partial \mathbf{x}} \right)_T \frac{d\mathbf{x}}{dP} = -\frac{1}{V_o} \left( \frac{\partial^2 G}{\partial P \partial \mathbf{x}} \right) \frac{d\mathbf{x}}{dP}$$

heat capacity

$$c_{p} = -T\left(\frac{\partial^{2}G}{\partial T^{2}}\right)_{p} = T\left(\frac{\partial S}{\partial T}\right)_{p} \implies \Delta C_{p} = T\left(\frac{\partial S}{\partial x}\right)_{p} \frac{dx}{dT} = -T\left(\frac{\partial^{2}G}{\partial T\partial x}\right)\frac{dx}{dT}$$
  
Thermal expansion coefficient

Thermal expansion coefficient

$$\boldsymbol{a} = \frac{1}{V_o} \left( \frac{\partial V}{\partial T} \right)_P \quad \Rightarrow \\ \Delta \boldsymbol{a} = \frac{1}{V_o} \left( \frac{\partial V}{\partial \boldsymbol{x}} \right)_P \frac{\partial \boldsymbol{x}}{\partial T} = \frac{1}{V_o} \left( \frac{\partial^2 G}{\partial P \partial \boldsymbol{x}} \right) \frac{\partial \boldsymbol{x}}{\partial T}$$

Therefore

$$\frac{\Delta C_{p}\Delta k}{V_{o}T(\Delta a)^{2}} = 1$$

### Linear non-equilibrium thermodynamics Equilibrium condition is:

- 1. All generalized forces  $X_k$  are zero (e.g.  $A_i^{eq} = 0$  chem. equilibrium)
- 2. There are no fluxes ;  $J_k=0$

This gives good reason to assume that close to equilibrium all generalized forces  $X_k$  are weak and fluxes can be expressed as a Taylor series

$$J_{k}(X_{l}) = J_{k}(0) + \sum_{l} \left(\frac{\partial J_{k}}{\partial X_{l}}\right) X_{l} + \frac{1}{2} \sum_{l,m} \left(\frac{\partial^{2} J_{k}}{\partial X_{l} \partial X_{m}}\right) X_{l} X_{m} + \dots$$

As the first term is zero the truncated series gives:

$$J_{k} = \sum_{l} L_{kl} X_{l} \qquad ; \qquad L_{kl} = \left(\frac{\partial J_{k}}{\partial X_{l}}\right)_{o}$$

This equation, together with the expression for the balance of mass is a complete system that permits an exact calculation of generalized forces or of the thermodynamic variables.

Essential point is the Onzager equation:

$$L_{ik} = L_{ki}$$

Onzager determines two dissipative functions

$$\boldsymbol{j}(X,X) = \frac{1}{2} \sum_{I,k} L_{ik} X_i X_k \ge 0$$
$$\boldsymbol{F}(J,J) = \frac{1}{2} \sum_{I,k} L_{ik}^{-1} J_i J_k \ge 0$$

These two functions are measures for local irreversibility. In the framework of linear approximation  $F = j = \frac{1}{2}s$ 

It can be shown that these functions have behaviour of potentials

$$\frac{\partial \boldsymbol{j}}{\partial x_i} = \sum L_{ik} X_i = J_i$$

and

$$\frac{\partial^2 \boldsymbol{j}}{\partial X_i \partial X_k} = \frac{\partial J_i}{\partial X_k} = L_{ik} = L_{ki} = \frac{\partial J_k}{\partial X_i} = \frac{\partial^2 \boldsymbol{j}}{\partial X_k \partial X_i}$$

# It follows that **j** , **F** and **s** are nonequilibrium potential functions

**Prigogine Principle** Stationary state is a state characterized with minimal entropy production for the given external conditions.

**In general** – The nonequilibrium processes proceed in such a way that forces are not increasing. Generalizing to nonlinear case is: The processes proceed in a way thet entropy production is not increasing

### EXAMPLE

Homogeneous multi-component system

$$\boldsymbol{s} = \sum_{i} w_i \, \frac{A}{T} \equiv \sum_{i} J \, \frac{A}{T}$$

According to the linear law:

$$\frac{d\mathbf{x}_i}{dt} = J_i = L_{ik} \frac{A_k}{T}$$

Near equilibrium

$$A \approx \frac{\partial A}{\partial \mathbf{x}} \left( \mathbf{x} - \mathbf{x}_{e} \right)$$

$$\frac{d\mathbf{x}}{dt} = \frac{L}{T} \frac{\partial A}{\partial \mathbf{x}} (\mathbf{x} - \mathbf{x}_e)$$

Solution is:

$$\mathbf{x} - \mathbf{x}_e = Ce^{-\frac{t}{t}}$$

The relaxation time is:  $t = -\frac{T}{L\left(\frac{\partial A}{x}\right)}$ 

**REM:** Strictly speaking  $w = \overrightarrow{w} \left[ 1 - exp \left( -\frac{A}{kT} \right) \right]$ Therefore linear approximation is valid for  $\left| \frac{A}{kT} \right| << 1$ 

### **Concluding Remarks**

We have seen that for isolated nonequilibrium systems  $d_eS>0$ . However, for open systems, it is possible to reach a stable stationary state corresponding to condition

 $d_e S = -d_i S < 0$ . This is to say that living organisms or society structures are possible if sufficiently large negative entropy fluxes flow through the systems.

Far from equilibrium, nonlinear systems of differential equations describe the processes. As there is no unique solution (unlike the linear case) of these systems, the Nature variety is guaranteed